

DYNAMIC MODELS FOR A HEAT-LED ORGANIC RANKINE CYCLE

- turbine and alternator models

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Content I

- 1 Introduction
 - System description
 - Cycle layout
 - Simulation scope
- 2 Modeling
 - Simulation method
 - Turbine
 - Alternator
 - Drive train
- 3 Validation & results
- 4 Conclusions
- 5 Acknowledgements
- 6 References

Motivation for the work

- 150 biomass based power plants all over Europe, 140 are heat-led
- many facilities are suffering from economic difficulties (fuel prices \uparrow , feed-in tariffs \downarrow , maintenance \uparrow)
- heat-led systems have limited degrees of freedom
- previous analyses have shown problems of control system regarding varying loads
- therefore, necessity for control optimisation

System overview I

Table : Design data of case study plant

-	Value	Unit
Thermal input	6356	kW
Temperature of source	300/240	°C
Thermal output	5300	kW
Temperature of sink	80/60	°C
Electric output	950	kVA
Mass flow	20	kg/s
Gross design efficiency	16.38	%

System overview II

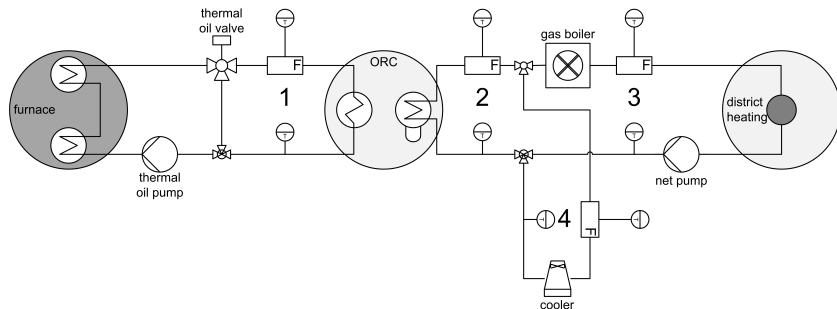


Figure : furnace, transfer system, ORC, cooling unit, district heating

- Fluids: thermal oil (T66), Octamethyltrisiloxane (MDM), water
- Heating curve is based on amb. temperature /ORC control is heat-led

Cycle layout

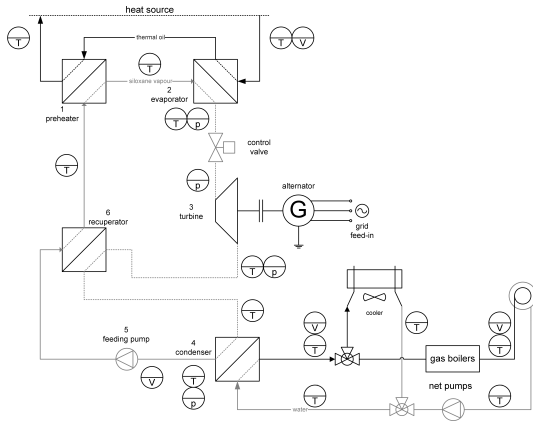


Figure : cycle including all relevant sensors

S7 / M-Bus → OPC gateway → OPC server/client → data base

Simulation scope I

Overall scope

- find compensation strategies for the controller
- find a suitable winter, summer and intermediate operation strategy

Partial scope

- dynamic generator model: improve validation, simulate start-stop procedures, alternator oscillation

→ a very accurate and robust turbine, alternator and drive shaft model with a wide load range is required.

Simulation method I

Method

- physical turbine model with empirical correlation for stage efficiency
- empirical alternator model based on design data of manufacturer
- physical drive train model
- validation through: measured electric output, $\sum \dot{m}$, frequency
- validation data for three different load ranges: high, medium, low

Tools

- steady state calculations, correlation fitting → MATLAB
- dynamic simulation → Dymola 2013 / modelica
- *ExternalMedia* Lib, *FluidPropMedium* Package, REFPROP [3]
- *ThermoPower* Lib

Turbine I

Turbine

- type: impulse, axial, single stage, super-sonic
- nozzle: 24 x De Laval, $\alpha = 19^\circ$, $\eta_{noz} = 92\%$
- turbine speed 3000 RPM $\rightarrow \bar{u} \sim 160$ m/s
- isentropic outflow velocity: 300 m/s
- lubrication system: separate
- frequency control: alternator/grid
- flow control: full admission, control (by-pass) valve for start-up
- mean rotor diameter 1 m

Turbine II



Figure : turbine, diffuser and aux. compounds

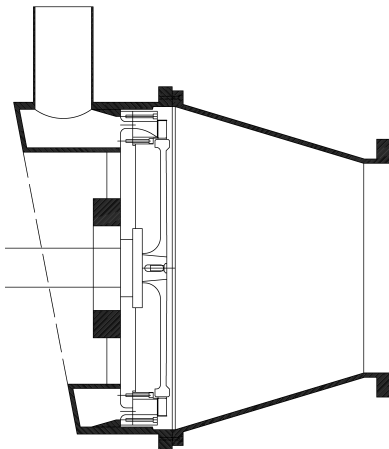


Figure : cross section of turbine and diffuser

Turbine III

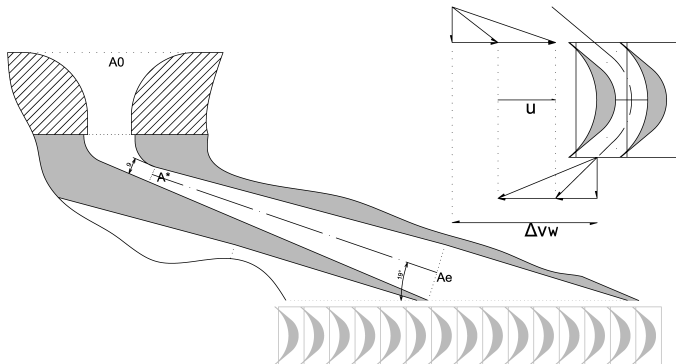


Figure : wrapped section of turbine nozzle and rotor

Turbine IV

Based on Stodola's Law of Cones [4] [5], Cooke [2] [1] proposed a model for multi-stage steam turbines:

$$\dot{m}_{turb} = k_T \times \sqrt{\rho_{in} \times p_{in}} \times \sqrt{1 - \left(\frac{p_{out}}{p_{in}} \right)^{\frac{\kappa+1}{\kappa}}} \quad (1)$$

The exponents of the pressure ratio r_s is usually set to 2 for steam turbines. The question is: what happens if one uses the κ of the organic fluid?

→ two model variants are tested: $\kappa = constant$, $\kappa = f(p, T)$

Turbine V

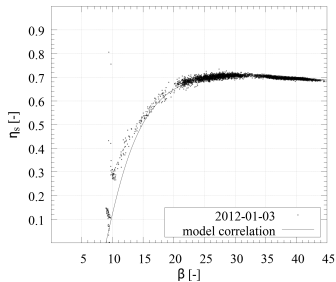


Figure : measured isentropic efficiency of turbine vs. correlation

$$\eta_s = a \times \text{atan} \left(b \times \beta^2 + \frac{c}{\beta} \right) + d \times \beta + f \quad (2)$$

Alternator I

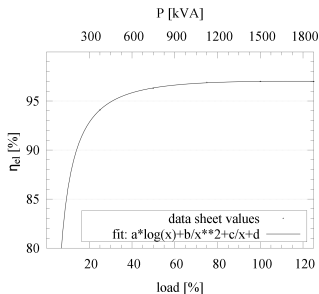


Figure : electric efficiency of alternator

- synchronous engine (50 ± 0.5 Hz), rated power 1500 kVA
- water cooled with separate cooling unit

Drive train I

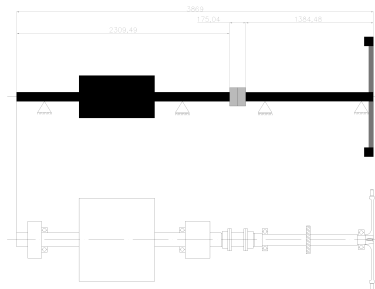


Figure : entire drive train, including bearings and couplings

- the friction has constant, linear and quadratic compounds
- simplification: bearing friction is a quadratic correlation $f(\omega)$
- tensor is calculated via measured shut down

Drive train II

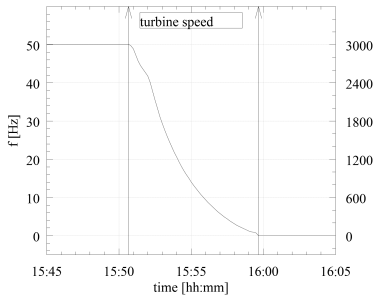


Figure : turbine shut-down vs. time

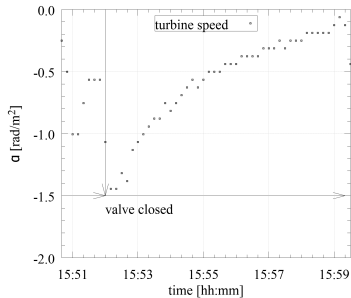


Figure : angular acceleration of rotor

- friction torque max. 63 Nm
- tensor 97.9 kg m²

Results I

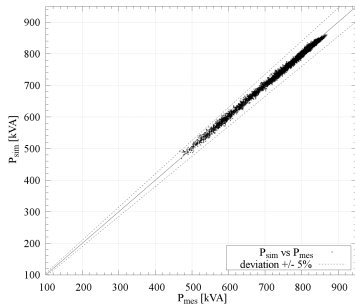


Figure : simulated vs. measured
(12-01-01)

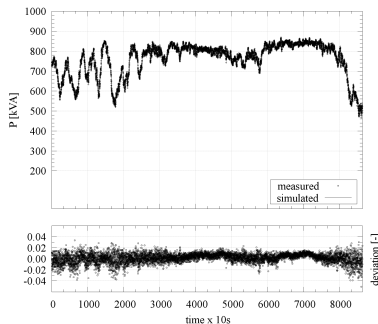


Figure : simulated and deviation vs.
time (12-01-01)

Results II

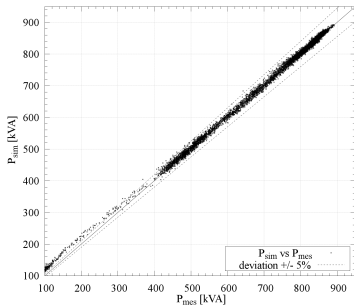


Figure : simulated vs. measured
(12-01-02)

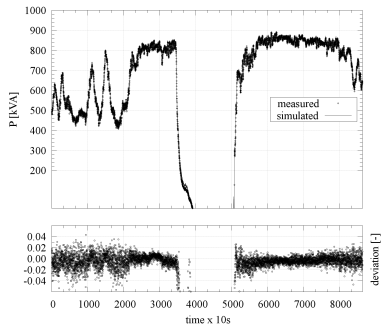


Figure : simulated and deviation vs. time
(12-01-02)

Results III

model	date	measured		simulated		deviation
		\bar{P}_{el}	W	\bar{P}_{el}	W	
-	[YYMMDD]	[kW]	[kWh]	[kW]	[kWh]	[-]
$\kappa = \bar{\kappa}$	12-01-01	760.28	18247	756.62	18159	-0.4821%
	12-01-02	592.47	14219	589.21	14141	-0.5491%
	12-01-03	338.38	8121	337.09	8090	-0.3823%
$\kappa(p, T)$	12-01-01	760.28	18247	756.62	18159	-0.4824%
	12-01-02	592.47	14219	589.17	18158	-0.5567%
	12-01-03	338.38	8121	337.06	8094	-0.3900%

Table : comparison of model and measured values for three data sets (1 day / 10 second steps)

Results IV

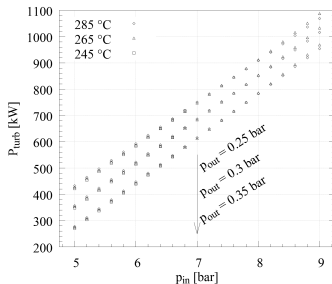


Figure : parameter study of turbine model

→ turbine provides maximum with low super-heating

Conclusions I

Conclusions

- measured values of isentropic efficiency give a good prediction for higher pressure ratios ($\beta \geq 15$)
- both model variants have a good prediction quality, the $\kappa = \text{const}$ -model needs less CPU
- k_t , $\tau_{fric}(\omega)$, polytropic exp, alternator: 4 parameters, η_s 5 parameters
- low super-heating is favourable, possible optimisation of the evaporator level
- for load changes under 10% both models have less than $\pm 2\%$ dispersion, maximum of $\pm 5\%$
- for 400 to 900 kW_{el} models have less than $\pm 2\%$ dispersion
- the cumulated work error for one day of operation is less than -0.5%

Conclusions II

Next steps

- testing the models with oscillating rotation frequency with data of higher precision

Thank you for your attention - Bedankt voor uw aandacht!

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Thanks to the modelica people

- [1] D.H. Cooke. Modeling of off-design multistage turbine pressures by Stodola's ellipse. *Proceeding PEPSE User Group Meeting*, pages 205–234, 1983.
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- [4] A. Stodola. *Steam Turbines - With an Appendix on Gas Turbines and the Future of Heat Engines*. Van Nostrand, Princeton, New Jersey, 1906.
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