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Preliminary design of a centrifugal turbine for ORC applications

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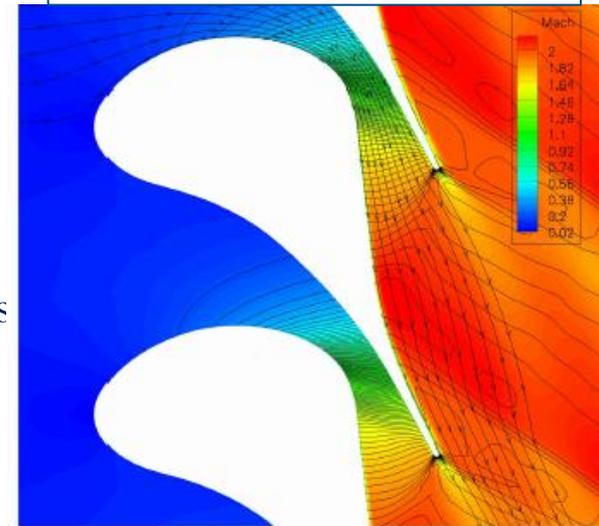
Unconventional thermodynamic expansion → unconventional turbines:

- High expansion ratios → large passage area ratio
- Small enthalpy drops → low number of stages / low peripheral speed
- Fluid (and flow..) complexity → low speed of sound, transonic/supersonic turbines

Scientific and technical issues

- Supersonic efflux of dense gases still under study
→ influence on turbine **efficiency** and **design criteria**
- State-of-art modelling tools necessary for reliable predictions
→ advanced **real-gas** models coupled with **CFD**

FluidProp & zFlow



Implementation of advanced modelling techniques into
present-day design tools for effective turbine design

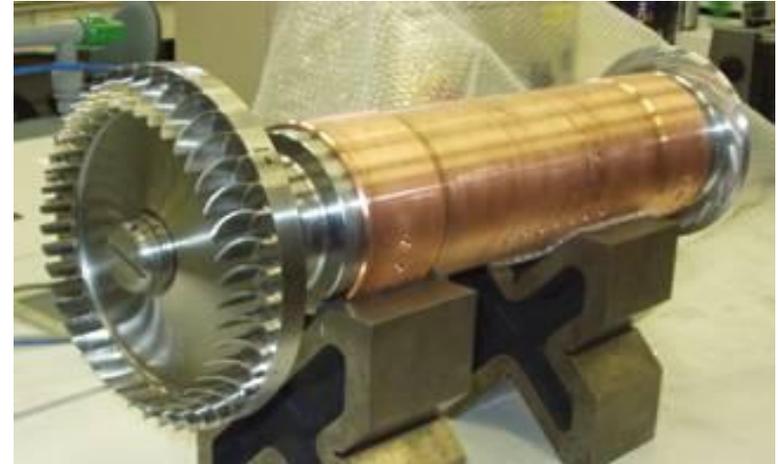
- Survey on turbine architecture
- Design methodology
- Design exercise of a multi-stage centrifugal turbine
- Conclusions and future works

Several architectures are possible

Axial turbines

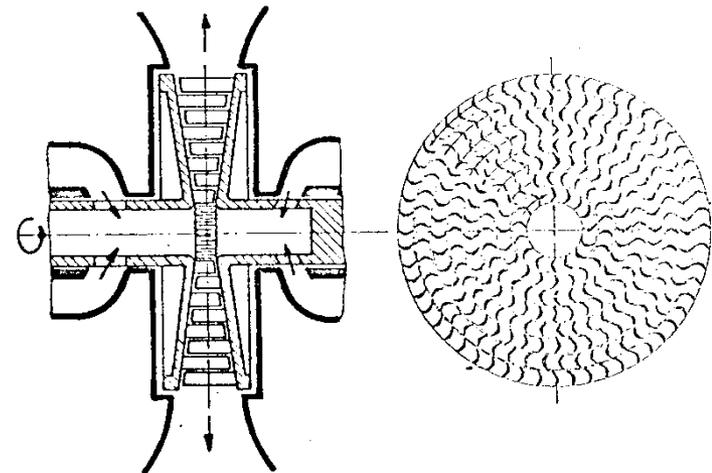


Centripetal turbines (radial inflow)



Centrifugal turbines (radial outflow):

- ✓ Counter-rotating (Ljungström)
- ✓ **Fixed-rotating centrifugal turbine**
already suggested by Macchi, VKI LS 1977
and Gaia et al., 1978



Advantages

- passage area naturally increases along the expansion process
→ fits with the huge increase of fluid specific volume
- more compact compared to equivalent axial turbines
→ higher number of stages → lower M, higher efficiency and flexibility

Main disadvantage:

- centrifugal force potential acts against work extraction
→ profile aerodynamics crucial for energy exchange effectiveness

$$L_{eu} = \frac{v_1^2 - v_2^2}{2} + \underbrace{\frac{u_1^2 - u_2^2}{2}}_{\text{Negative term}} - \frac{w_1^2 - w_2^2}{2}$$

Negative term ($u_2 > u_1$)



Reduction of work

- Survey on turbine architecture
- **Design methodology**
- Design exercise of a multi-stage centrifugal turbine
- Conclusions and future works

Overview on design strategy

Difficult task due to the thermodynamic complexity, and transonic flow
Specific turbine design, depending on fluid and thermodynamic conditions

Design techniques:

- ✓ **1D** mean-line method, still used, suited for **initial design** and optimization
- ✓ CFD simulations, three dimensional, steady or unsteady, for blade definition
- ✓ Necessity of a **bridge between 1D and 3D** approach: **throughflow** method
 - **axisymmetric** assumption, including losses, flow deflection and blade blockage: define the ‘mean-surface’ of the flow across the whole machine
 - effects of shocks, post-expansion, annulus boundary layers and flaring are included

**1D meanline
(preliminary design)**



**Throughflow
(flow surface)**



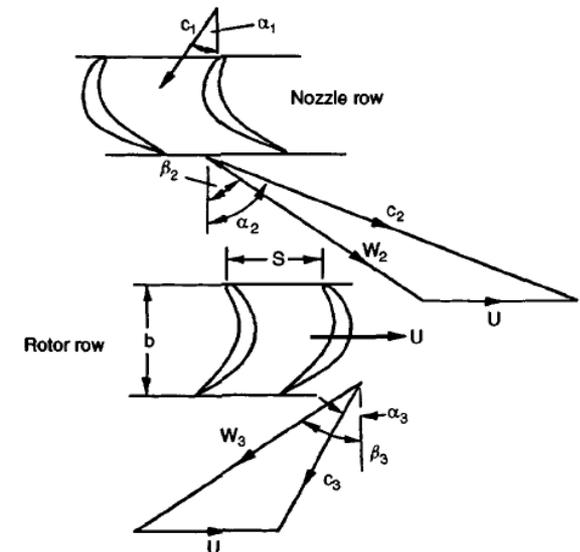
**Fully 3D simulation
(blade refinement)**

The 1D mean-line code

- Based on **mass** conservation, **energy** balance, estimate of **polytropic index**
- Criteria to divide the expansion ratio across the stages and blade rows (χ)
- Geometrical assumptions: inlet h/D , discharge blade angles
- Blade span along the machine computed through mass conservation (choking)
- Work exchange computed from velocity triangles
- Entropy production predicted by **loss correlation** (es. Soderberg, Traupel, Craig&Cox)

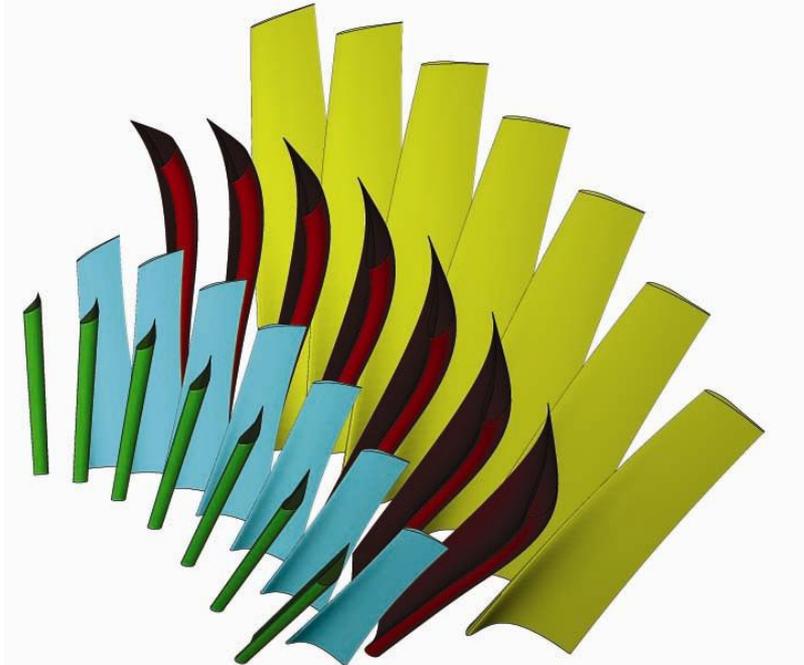
Code main features

- ✓ Applicable to the design of axial and radial turbines
- ✓ Coupled with FluidProp (Prof. Colonna, TU Delft) for thermodynamic properties calculation
- ✓ Directly connected with the throughflow solver

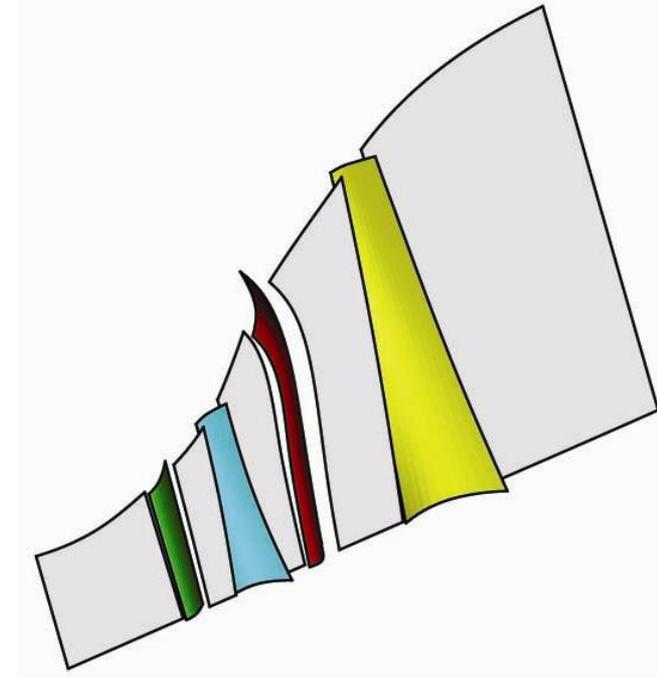


Throughflow concept

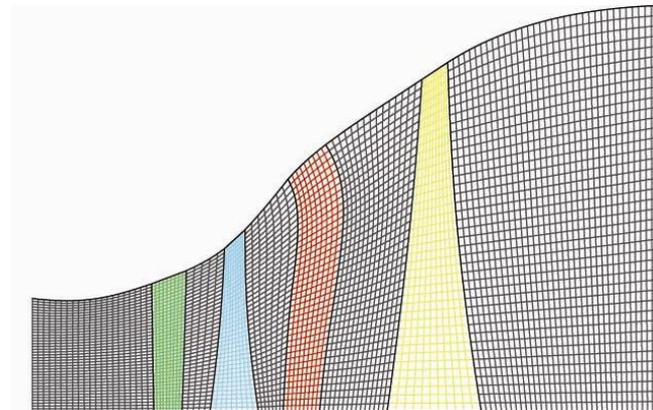
Multistage LP axial turbine: fully 3D
unsteady: CFD affordable but with very high computational cost (no optimization)



Axisymmetric flow assumption



2D problem: very fast
hours → minutes



Intrinsically suitable
for optimization



CFD-based throughflow model

Axisymmetric inviscid model with volume forces: deflection (**L**), losses (**D**)

$$\frac{\partial \mathbf{u}}{\partial t} + \frac{\partial \mathbf{f}^x}{\partial x} + \frac{1}{r} \frac{\partial (r \mathbf{f}^r)}{\partial r} + \frac{1}{r} \mathbf{s}^r + \frac{1}{b} \frac{\partial b}{\partial x} \mathbf{f}^x + \frac{1}{b} \frac{\partial b}{\partial x} \mathbf{f}^r + \mathbf{s}^b = \mathbf{s}^v$$

$$\mathbf{u} = \begin{bmatrix} \rho \\ \rho e_0 \\ \rho v_x \\ \rho v_r \\ \rho v_\theta \end{bmatrix}, \quad \mathbf{f}^x = \begin{bmatrix} \rho v_x \\ \rho h_0 v_x \\ \rho v_x^2 + P \\ \rho v_r v_x \\ \rho v_\theta v_x \end{bmatrix}, \quad \mathbf{f}^r = \begin{bmatrix} \rho v_r \\ \rho h_0 v_r \\ \rho v_x v_r \\ \rho v_r^2 + P \\ \rho v_\theta v_r \end{bmatrix}, \quad b(x, r) = \frac{N[\theta_p(x, r) - \theta_s(x, r)]}{2\pi}$$

$$\mathbf{s}^r = \begin{bmatrix} 0 \\ 0 \\ 0 \\ -(\rho v_\theta^2 + P) \\ \rho v_r v_\theta \end{bmatrix}, \quad \mathbf{s}^b = \begin{bmatrix} 0 \\ 0 \\ -P \partial b / \partial x \\ -P \partial b / \partial r \\ 0 \end{bmatrix}, \quad \mathbf{s}^v = \begin{bmatrix} 0 \\ \rho(\mathbf{L} + \mathbf{D}) \cdot \omega r \mathbf{e}_\theta \\ \rho(\mathbf{L} + \mathbf{D}) \cdot \mathbf{e}_x \\ \rho(\mathbf{L} + \mathbf{D}) \cdot \mathbf{e}_r \\ \rho(\mathbf{L} + \mathbf{D}) \cdot \mathbf{e}_\theta \end{bmatrix}$$

$$\mathbf{L} = L \mathbf{n}_g \longrightarrow L = L(\mathbf{u}) = -K \mathbf{w} \cdot \mathbf{n}_g = -K (\mathbf{v} - \omega r \mathbf{e}_\theta) \cdot \mathbf{n}_g$$

$$\mathbf{D} = -D \mathbf{t} = -D \frac{\mathbf{w}}{\|\mathbf{w}\|} \longrightarrow D = T \nabla_s \cdot \frac{\mathbf{w}}{\|\mathbf{w}\|} = T \nabla_s \cdot \mathbf{t}$$

Numerical scheme

- Implemented as an extension of the $\mathcal{z}Flow$ code (Prof. Rebay, Univ. of Brescia)
- Based on hybrid FE/FV formulation, uses fully implicit time-marching methods
→ very efficient and accurate computational model (especially for 2D problems)
- Coupled with FluidProp (Prof. Colonna, TU Delft) for thermodynamic properties
→ accurate treatment to handle arbitrary EoS (thus to deal with organic fluids)

Blade modeler & grid generator

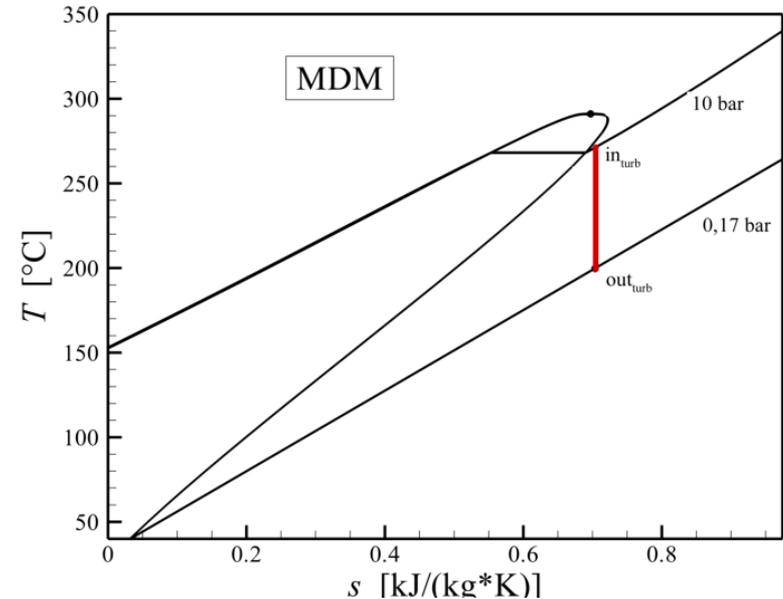
- Throughflow solver integrated by a blade modeler with mesh generator
- Blade mean line and blockage factor managed through a generalized blade modeler
- Structured multi-block mesh generator for axial, radial and mixed-flow machines

1. The radial-outflow turbine
2. Turbine design method
- 3. Design exercise of a multi-stage centrifugal turbine**
4. Conclusions and future works

Design exercise: 1D mean-line design

Turbine case: 'mainstream ORC'

- Inlet thermodynamic conditions:
 - ✓ Total inlet T: **274 °C**
 - ✓ Total inlet P: **10 bar**
- Working fluid: **siloxane MDM**
- Expansion ratio: **60**
- Target power: **1÷2 MW**



Design constraints:

- $M_{MAX} = 1.1$
- $\chi \approx 0.5$
- $\psi_{MAX} = 30^\circ$

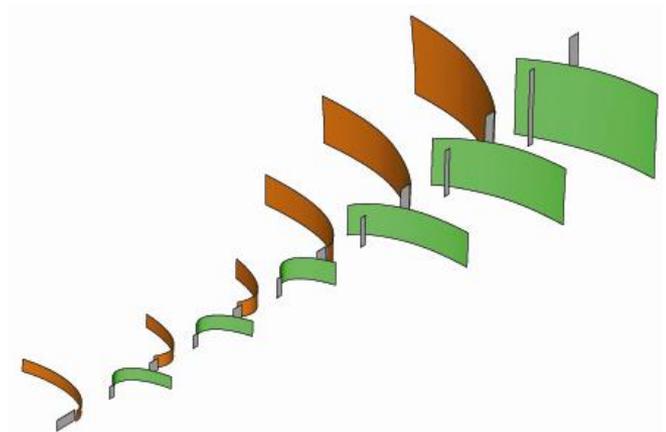
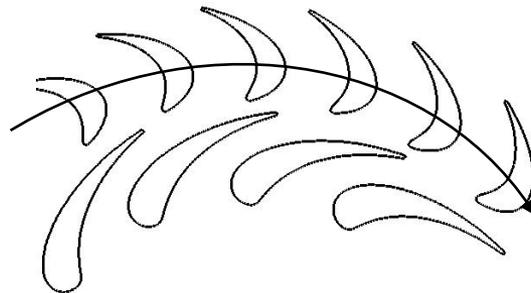
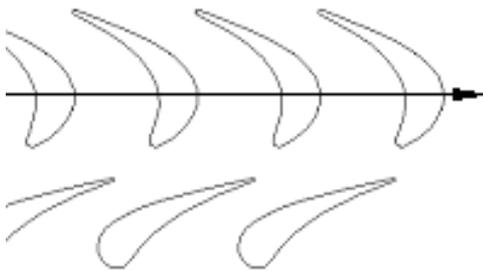
Outcome of parametric study:

- $N_{ST} = 6$
- $R_{EXT} = 0.7$ m
- $n = 3000$ rpm
- $P = 1.3$ MW
- $\eta_{TS} = 0.894$

Stage	$P_{T,out}$ (bar)	P_{out} (bar)	T_{out} (°C)	s (kJ/kgK)	W (%)
1	5.62	5.07	261.5	0.718	11.6
2	2.72	2.57	253.5	0.720	17.3
3	1.34	1.30	246.7	0.722	18.6
4	0.70	0.66	240.2	0.723	18
5	0.37	0.34	234	0.724	17.8
6	0.20	0.17	227.7	0.725	17.6

From lumped-parameter mean-line to continuous mean-blade-surface

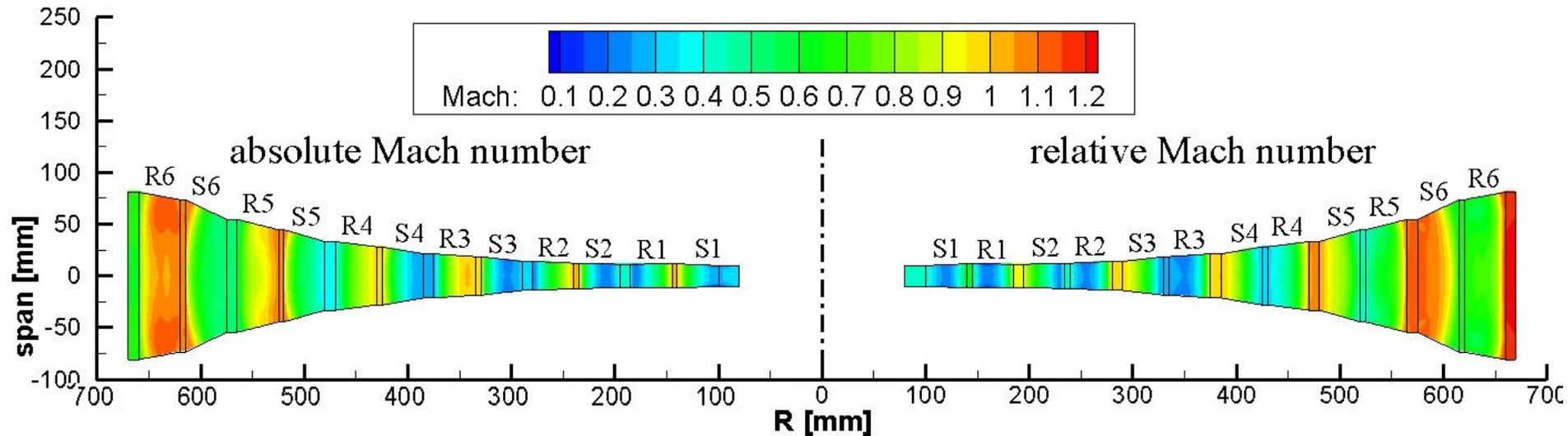
- Design of meridional channel
 - blade span evolution along the machine from 1D model
 - relevant risk of separation close to the endwalls (gaps act as vaneless diffusers)
 - constant flaring angle in each bladed region, inter-row gaps as small as possible
- Definition of the blade shape: mean line and blade thickness
 - basic 2D profiles developed for axial turbines
 - profile deformation to match in/out design blade angles
 - conformal transformations in polar coordinates to conserve blade angles



Design exercise: throughflow calculation

Soderberg correlation for core flow + annulus boundary layer loss model

21 (span) x 400 (stream) grid, computational time ~5 min



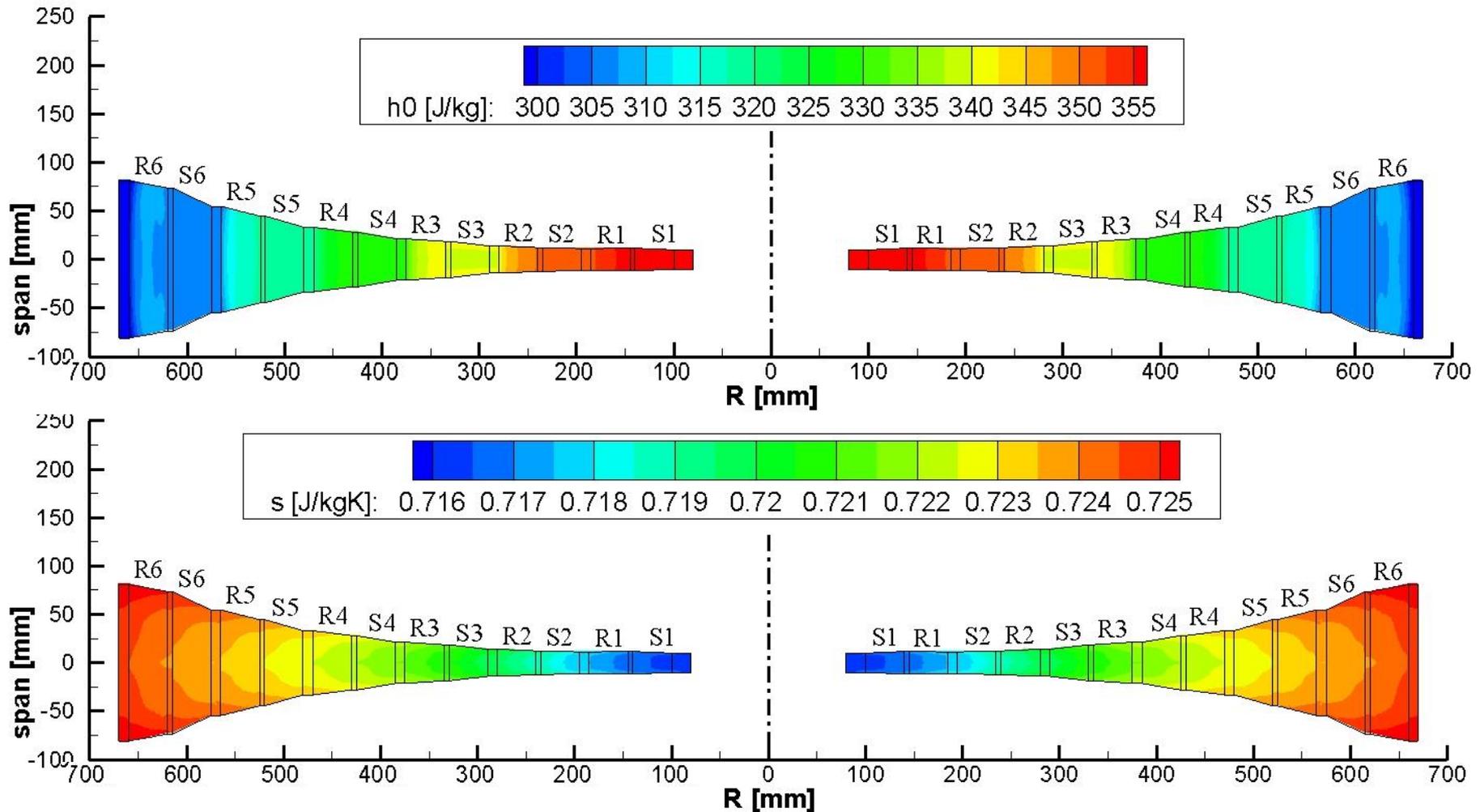
Flow distribution on the whole meridional surface

Maximum abs/rel Mach number target nearly confirmed (1.1)

Significant deviations from 1D model in the last stages

Design exercise: throughflow calculation

Streamwise evolution of thermodynamic quantities



Computed efficiency 88.8% ($< 0.5\%$ 1D)

- Multistage centrifugal turbine architecture considered
- Design methodology for multistage ORC turbines proposed, based on:
 - . mean-line code
 - . CFD-based throughflow model
- Design exercise for a ‘mainstream’ ORC turbine ($P \sim 1.3$ MW, $P_t = 10$ bar, $T_t = 270^\circ\text{C}$)
 - 6 stages, 3000 rpm, $R = 0.7$ m, $\eta \sim 89\%$
- Throughflow model: 1D integral data corrections, large spanwise gradients
- Future work will move mainly in three-directions:
 - blade-to-blade calculations to update loss and slip factor correlations
 - unsteady calculations to investigate blade-row interaction (very small gaps!)
 - coupling with optimization methods to determine the optimal streamsurface

THANK YOU!

